



RC - TT Automatic CNC thermal coping lines for profiles notching





The modern structural steel buildings are made with profiles (beams, U-channels, angles, tubes) that are joined and bolted one to the other.

Straight and mitred cuts are carried out with modern sawing systems, shaped cuts on profile edges or on web and flanges, instead have always been a problem that is today brilliantly solved thanks to the Ficep thermal coping robots.

The Ficep robot allows the torch to move and orientate (using plasma or oxyfuel cutting). It is also possible to carry out coping of programmed shapes previously stored in the CNC library.

The robot is controlled by dedicated software which gives simple and essential sequences:

1. The torch carries out the probing cycle to survey the real values of the piece to be processed;

2. These real values are compared with the theoretical ones registered in the CNC library; any discrepancies are automatically corrected and the torch will move to the exact position to start the cycle, once the cut is finished, the piece always detaches itself without problem!

3. The required shape is chosen from the relevant library and only its real dimensional values must be loaded into the program; no time is lost to reprogramme the shape; the shapes in the library which are normally required in steel construction are all already programmed;

4. The torch automatically starts and carries out the cutting of the shapes and can be repeated continually without mistakes.



The advantages of these systems are straight forward and obvious:

- All the manual operations to measure, mark out and cut disappear;
- · Values are respected with no mistakes;
- Cutting operations can be done in line with drilling units in order to save time;
- The processing cycle is optimized;
- The manufacturing times are drastically reduced;
- Processing is done in a complete automatic and tidy way;
- The spaces dedicated to this kind of processing are reduced;
- · Production costs are lowered;
- The labour required for complicated operations is reduced to the minimum.





Thermal coping system mod. TT complete with rollerways and transfer tables with carts.



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• Carriage, with a pincher that can be adjusted in all the directions, for the longitudinal positioning of 12 mt long bars. The carriage is equipped with a suitable supporting structure and allows the profiles to move on idle rolls.

• Machine chassis consisting of four columns in electrowelded steel tubes to support the robot.

• Semi-spherical cartesian robot with 6 controlled axes holding the oxycutting torch.

• Torch equipped with a device to automatically survey and compensate profiles values and dimensional tolerances.

• Automatic vices to guarantee perfect material clamping even during cuts where the material moves longitudinally.

• Hydraulic alignment device between the first two rolls of the infeed rollerway.

• System for detection and automatic adjustment of dimensional tolerances.

• 12 mt powered rollerway to unload the processed pieces.

• Ficep ARIANNA control unit the latest generation controlling 6 axes.



Hydraulic clamping vices

Oxycutting torch













- Plasma cutting system with Hypertherm power source.
- · Smoke intake system which is essential with the plasma torch cutting.
- · Infeed and outfeed rollerways for 16 mt or 20 mt long profiles.
- · Infeed and outfeed transfer tables with catches or carts.





Smoke intake system

CNC Line with "RC" Thermal coping unit and "DF" Drilling unit in tandem Plasma torch

Mobile system to survey the piece values on the lower side





















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3D graphic simulator of the robot this show's the virtual processing to be done.

• Point-to-point LEAD CUT programming done directly by the on-board CNC;

• Programming through graphic macros that are already stored and registered in the relevant library;

- Programming through data import from an off line computer;
- Automatic survey of the component for precise torch positioning





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HARDWARE and SOFTWARE

The new generation control unit, with controlled axes, is based on a fieldbus CANopen technology.

The CNC is positioned on a pedestal in a mobile control panel, so that the operator can have a complete view of the machine.

All the input and output cards are connected to the bus and lodged on the machine, if it's possible.

The CNC is equipped with:

- digital inputs (24V optoinsulated)
- digital outputs (24V protected transistors)

The control panel is an industrial PC containing the CNC and having the following specifications:

- 600 Mhz CPU with L2 512 KB "cache"
- 512 MB RAM memory
- Touch screen colour video TFT 12.1"
- Keyboard panel and auxiliary pushbutton panel
- 10/100 RJ45 Ethernet port
- USB modem
- 1 additional USB port
- WINDOWS XP Embedded operative system
- Teleservice software

Programming

- Simplified data input (with tables and workpiece on-screen graphics)
- Absolute and incremental values
- Nesting of equal or different workpieces into the same bar, with on-screen graphics
- Automatic nesting

Processing

- Automatic tool assignment
- Unit offset sum
- Values ordering

Automatic optimization on the basis of the quantities left for each single workpiece.

Execution

• Automatic survey of the bar length, and recalculation of the optimized accumulation

All the indications are clearly displayed on the screen, and concern:

- Current program indication, with clear description of the program running at the moment
- CNC inside and outside alarms

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- Registration of the date and time of the last 100 alarm messages
- Diagnostic messages to the operator.

The supply also includes:

- Software "GS-TT" package to program coping shapes through preset parametric macrographics, as shown in the attached table.
- Software package to obtain equal or different pieces from one bar with the coping shapes of the "GS-TT" software package.



TECHNICAL SPECIFICATIONS & PRODUCTIVITY DATA

Models	1201 RC	2061 TT
Profiles that can be processed:		
I-Beams (without camber) Web height Web height	min. mm 80 max. mm 1220 min. mm 42 max. mm 600	min. mm 200 max. mm 2000 min. mm 60 max. mm 600
U-channels (web downwards) Web height Flange width	min. mm 80 max. mm 1220 min. mm 45 max. mm 600	min. mm 200 max. mm 2000 min. mm 60 max. mm 600
Angles Flange height (unequal flanges as well)	min. mm 80x80x8 max. mm 300x300x50	min. mm 200x200x15 max. mm 500x500x40
All sections Maximum length (can be expanded with options)	mm 12000	mm 12000
Minimum transferable length (with longitudinal copes on both heads having a maximum length of 400 mm on the lower half flanges)	mm 2500	mm 2500
Positioning weight	Kg 6000	Kg 10000
Linear weight of the section	Kg/m 375	Kg/m 500
Carriage speed	m/min 40	m/min 40
CNC Ficep Minosse axes	no. 7	no. 6



via Matteotti, 21 21045 GAZZADA SCHIANNO VA - ITALY Tel. +39 0332 876.111 Fax +39 0332 462.459 www.ficep.it E-mail: ficep@ficep.it



Z.I. "Les Platanes" - B.P. 20 33360 CAMBLANES - FRANCE Tel. +33 (0) 556.20.15.55 Telefax +33 (0) 556.20.15.56 www.ficep-france.fr E-mail: ficep@ficep-france.fr



Poligono Industrial Ali-Gobeo Calle Becolarra, N2 - Pabellón 30 01010 VITORIA (ALAVA) - SPAIN Tel. +34 945.14.83.11 Fax +34 945.14.81.37 www.ficepiberica.com E-mail: ficep@ficepiberica.com



Office, Tele/fax 0044-2886751150 Mobile 0044-7711610244 Office, Tele/fax 0044-1460239635 Mobile 0044-7876591176



10 The Courtyards - Victoria Park Victoria Road,Leeds LS14 2LB - UNITED KINGDOM Sales Tel: 0113 2653921 Service Tel: 0113 2653923 Fax: 0113 2653913 www.ficep.co.uk E-mail: info@ficep.co.uk



Bernhard-Hahn-Str. 7-9 41812 Erkelenz GERMANY Tel. 02431-80020 Fax 02431-800213 www.ficep-hmb.de E-mail:info@ficep-hmb.de



2301 Industry Court - Forest Hill Industrial Park FOREST HILL, MD 21050 USA Tel. 1-410-588-5800 Fax 1-410-588-5900 www.ficepcorp.com E-mail: info@ficepcorp.com



Unit 204, 2nd Floor - Block C DB Plaza Discovery Bay - HONG KONG Tel, +852-2544 6888 Fax +852-2544 5123 www.ficep.com.hk E-mail: info@ficep.com.hk



144 El-Alam Str. Forest Bidg., Badaro PO.Box 2019/116 Beirut Court House Beirut - LEBANON Tel. +961 1 386664 Fax +961 1 386011 Mobile: +961 70126826 www.ficep-me.com E-mail:dirar.h@ficep-me.com